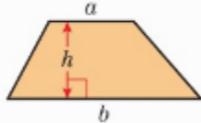
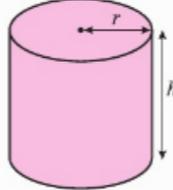
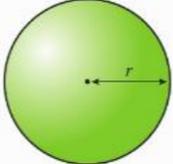
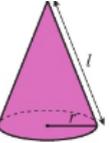




MATHEMATICS - YEAR 9 HIGHER TERM 3

A AREA AND VOLUME		
1	Area of a Trapezium	$= \frac{1}{2}(a+b)h$ 
2	Units	$1\text{cm}^2 = 100\text{mm}^2$ 1 hectare (ha) = 10000m^2
3	Error Interval	The range of values within which a rounded number could be. E.g. a value rounded to the nearest integer is 13, The error interval is $12.5 \leq x < 13.5$
4	Volume	The space within a 3D shape (m^3 , mm^3 , cm^3)
5	Capacity	The volume of liquid that fits within a 3D shape (ml, litres). $1\text{cm}^3 = 1\text{ml}$
6	Surface Area	The total area of all faces of a 3D shape
7	Prism	A 3D shape with a constant cross-section
8	Volume of a Prism	Area of cross-section x length
9	Circumference	The perimeter of a circle. $C = \pi d$ or $C = 2\pi r$
10	Area of a Circle	$A = \pi r^2$
11	Cylinder	The volume of a cylinder of radius r and height h is: $V = \pi r^2 h$ The surface area of the same cylinder is: $S.A. = 2\pi r^2 + 2\pi r h$ 
12	Sphere	For a sphere of radius r : Surface Area = $4\pi r^2$ Volume = $\frac{4}{3}\pi r^3$ 

13	Volume of a Pyramid	$\frac{1}{3}$ area of base x vertical height
14	Cone	Volume = $\frac{1}{3}\pi r^2 h$ (h is vertical height) Surface area = $\pi r l + \pi r^2$ (l is the slant height, $\pi r l$ is the curved surface area) 

B TRANSFORMATIONS AND CONSTRUCTIONS		
1	Views	From above is called the plan view, from the front is the front elevation and the side is the side elevation
2	Transformation	Moves a shape to a different position. Types include: Translation, Reflection, Rotation and Enlargement.
3	Object	An original shape pre-transformation
4	Image	The result of a transformation
5	Rotation	The object rotates. Moves by an angle, (anti)clockwise and from a centre of rotation. Object and Image are congruent.
6	Enlargement	A change in size (larger or smaller). Moves using a scale factor and from a centre of enlargement. Object and image are similar. Area increases by the (scale factor) ²
7	Translation	The shape moves position only. It is described by a column vector e.g. $\begin{pmatrix} 2 \\ -3 \end{pmatrix}$ meaning 2 right, 3 down. Object and image are congruent
8	Reflection	The shape reflects over a mirror line which can be an equation. Object and image are congruent
9	Resultant Vector	Where several vectors combine into 1 single vector
10	Bearings	An angle measured clockwise from north, given as 3 digits, used for directions



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B

TRANSFORMATIONS AND CONSTRUCTIONS

11	Construct	Draw accurately using a ruler and compass
12	Perpendicular Bisector	Cuts a line exactly in half at 90°
13	Angle Bisector	Cuts an angle exactly in half
14	Locus	A set of points that obey a rule
15	Locus: fixed distance from a Point	A circle drawn around the point
16	Locus: Equidistant from 2 Points	Points lie on the perpendicular bisector
17	Locus: Equidistant from 2 Lines	Points lie on the angle bisector